

OptiY 4.7

Data-driven Modeling and Simulation based on Physics-informed Machine Learning

October 2023 - OptiY GmbH

Hilbert Space

User-friendly Framework for Machine Learning and Modeling
(Regression and Classification = Analog and Digital Simulation)

- Polynomial Vector**

$$\phi_d = \{1, x_d, x_d^2, x_d^3, \dots, x_d^n\}$$

- Dirichlet Kernel Vector**

$$\phi_d = \{1, \cos(x_d), \cos(2x_d), \cos(3x_d), \dots, \cos(nx_d)\}$$

- User-Defined Vector**

$$\phi_d = \{f_1(x_d), f_2(x_d), f_3(x_d), f_4(x_d), \dots, f_n(x_d)\}$$

$$\phi(x) = \phi_1 \otimes \phi_2 \otimes \phi_3 \dots \otimes \phi_d$$

$$x = \{x_1, x_2, x_3, \dots, x_d\}$$

<input type="checkbox"/> Hilbert Space	
Uniform Space	<input checked="" type="checkbox"/>
Covariance Function	User Defined
<input type="checkbox"/> Number of Features	
1	1
2	cos(p1*x1)
3	cos(p2*x2)
4	cos(2*p1*x1)
5	cos(2*p2*x2)
6	cos(3*p1*x1)
7	cos(3*p2*x2)
8	cos(4*p1*x1)
9	cos(4*p2*x2)
<input type="checkbox"/> Optimization Parameter	
Number of Parameters	2
<input type="checkbox"/> Parameter 1	
Name	p1
Value	1
Lower Boundary	0
Upper Boundary	2
<input type="checkbox"/> Parameter 2	
Name	p2
Value	1
Lower Boundary	0
Upper Boundary	2
Gaussian Noise [%]	0.01
Approximation Error [%]	0

Linear and Nonlinear Solvers for Hilbert Space

- Reproducing Kernel Hilbert Space**

$$k(\mathbf{x}, \mathbf{x}') = \sum \phi(\mathbf{x}) \cdot \phi(\mathbf{x}')$$

$$L = \log|\mathbf{K}| + \mathbf{y}^T \mathbf{K}^{-1} \mathbf{y}$$

Marginal Likelihood Function

- Nonlinear Method (Neural Networks)**

$$L = \sum_{i=1}^m (\phi(\mathbf{x}_i) \cdot \boldsymbol{\beta} - y_i)^2 + R$$

Loss Function L + Regularization R
Nonlinear Least-Square Method

New Optimization Methods

L-BFGS
Stochastic Gradient Descent
Gauss-Newton

<input type="checkbox"/> Kernel Method	
Max. Order	10
Noise-Optimization	<input type="checkbox"/>
Optimization Method	Gradient Based
Max. Iterations	30
<input type="checkbox"/> Nonlinear Method	
Include Hilbert Space	<input type="checkbox"/>
Weight Optimization	<input type="checkbox"/>
Regularization	None
Optimization Method	L-BFGS
Max. Iterations	50

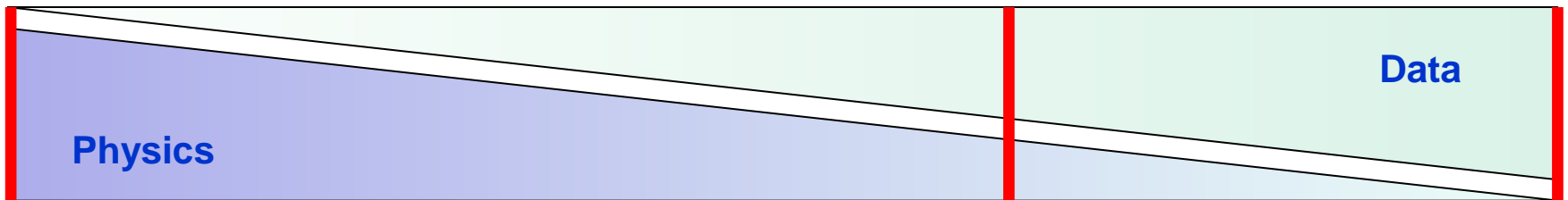
Physics-informed Machine Learning (PIML)

Physics-Model

- Physical laws by partial differential equations, boundary/initial conditions and constraints.
- Model validation through some measurement data possible.
- Serial implementation and **long computing time**.

Data-Model

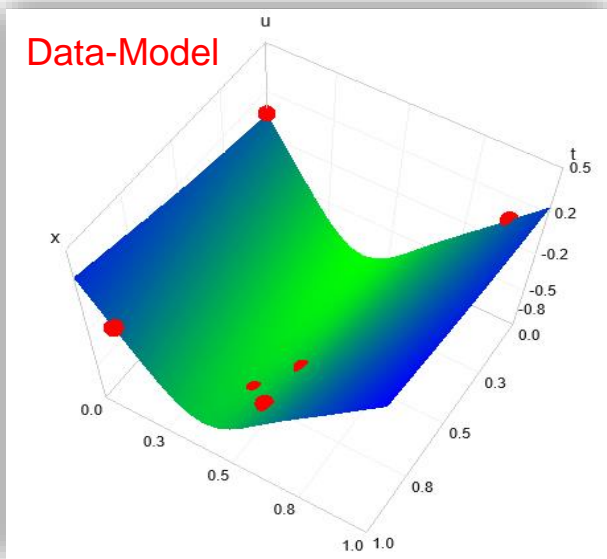
- Measurement data from prototype. (huge data required)
- Physical laws not necessary.
- Machine learning (regression and classification) automatically.
- Parallel implementation and **real-time computing**.



Data-driven Modeling and Simulation based on PIML

- Any **mix** from some data and some physical components
- Parallel Implementation and **real-time computing**

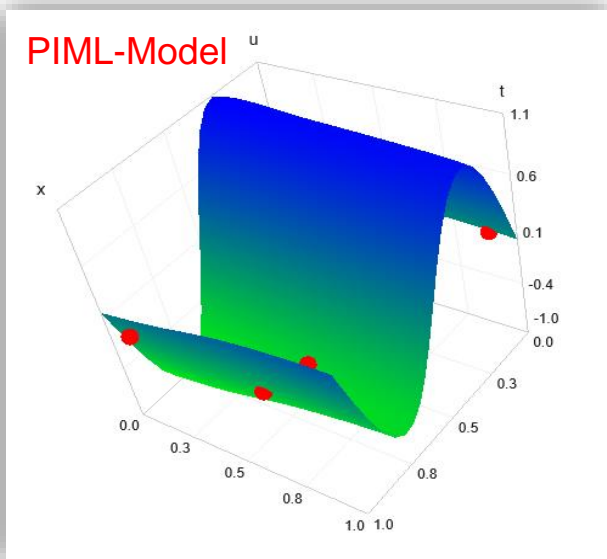
Case Comparison: Data vs. PIML



<input checked="" type="checkbox"/> Hilbert Space	
Uniform Space	<input checked="" type="checkbox"/>
Covariance Function	Matérn Class 3/2
Number of Features	12
Gaussian Noise [%]	0.01
Approximation Error [%]	0
State Variables	<input type="checkbox"/>
Partial Differential Equation	<input type="checkbox"/>
Boundary Conditions	<input type="checkbox"/>
Constraints	<input type="checkbox"/>
Parameters	<input type="checkbox"/>

Data

Data-model from only some data points is **inaccurate and not useable**.



<input checked="" type="checkbox"/> Hilbert Space	
Uniform Space	<input checked="" type="checkbox"/>
Covariance Function	Matérn Class 3/2
Number of Features	12
Gaussian Noise [%]	0.01
Approximation Error [%]	0
State Variables	<input type="checkbox"/>
<input checked="" type="checkbox"/> Partial Differential Equation	
PDE	$\text{derivate}(u,t) - \text{derivate}(u,x,x) = \exp(-t) * (4 * \pi * \pi - 1) * \sin(2 * \pi * x)$
Linear	<input checked="" type="checkbox"/>
Sampling Level	10
User Defined	<input type="checkbox"/>
<input checked="" type="checkbox"/> Boundary Conditions	
Number of Boundaries	1
<input checked="" type="checkbox"/> Boundary 1	
Boundary Function	$u=0$
<input checked="" type="checkbox"/> Number of fixed Values	1
Fixed Parameter	x
Value	0
Sampling Level	10
User Defined	<input type="checkbox"/>
Constraints	<input type="checkbox"/>
Parameters	<input type="checkbox"/>

Same Data

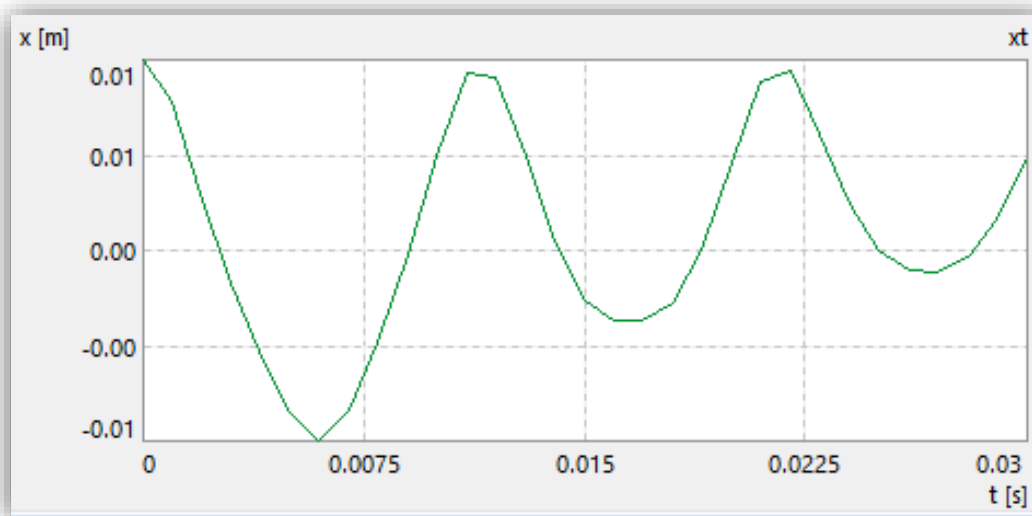
Partial Differential Equation

Boundary Condition

PIML-model from same data and some physical components is **accurate and useable**

Dynamical Systems / 1D-Systems

- Combination from machine learning and numerical integration (Euler, Heun, Runge-Kutta)
- **Strong nonlinear systems**
- **Multiphysics** with different disciplinary fields (Heat, Fluid, Static, Current, Energy etc.)
- **Interactions** between different partial systems

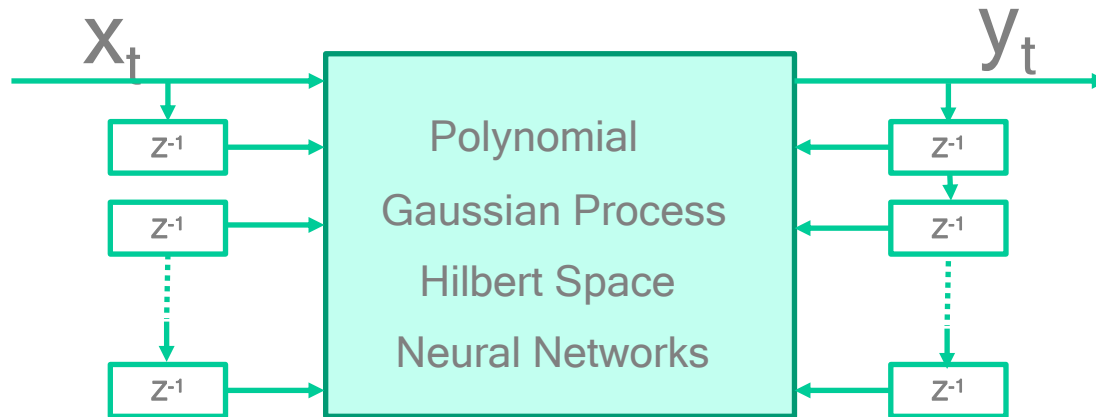


1D-Variables	
X-Max	0.03
X-Step	0.0001
X-Integration	Euler

Hilbert Space	
Include X-Axis	<input checked="" type="checkbox"/>
Include 1D-Variables	<input type="checkbox"/>
X-Nonlinearity	None
Uniform Space	<input type="checkbox"/>
k	
Covariance Function	Polynomial
Order of Feature	2
t	
Covariance Function	Exponential
Number of Features	12
Gaussian Noise [%]	0.01
Approximation Error [%]	0
State Variables	<input type="checkbox"/>
Partial Differential Equation	
PDE	$m/k \cdot \text{derivate}(xt,t,t) + c/k \cdot \text{derivate}(xt,t) + xt = 1/k$
Linear	<input checked="" type="checkbox"/>
Sampling Level	10
User Defined	<input type="checkbox"/>
Boundary Conditions	
Number of Boundaries	2
Boundary 1	
Initial Value	$xt=0.02$
Number of fixed Values	1
Fixed Parameter	t
Boundary 2	
Initial Value	$\text{derivate}(xt,t)=0$
Number of fixed Values	1
Fixed Parameter	t
Constraints	<input type="checkbox"/>
Parameters	<input type="checkbox"/>

Nonlinear Autoregressive Exogenous Model (NARX) for 1D-Systems

- Autoregressive components with exogenous variables
- Specific structure and architecture depending on the problem.
- 1D-modeling for **strong nonlinear systems**
- Data-driven **discovery of partial differential equations**



<input type="checkbox"/> Hilbert Space	
Include X-Axis	<input type="checkbox"/>
<input type="checkbox"/> Include 1D-Variables	<input checked="" type="checkbox"/>
xt	<input type="checkbox"/>
vt	<input type="checkbox"/>
ut	<input checked="" type="checkbox"/>
X-Nonlinearity	Autoregressive Exogenous Model
X-Input Order	2
All X-Input Orders	<input checked="" type="checkbox"/>
X-Output Order	2
All X-Output Orders	<input checked="" type="checkbox"/>
Uniform Space	<input checked="" type="checkbox"/>
Covariance Function	Polynomial
Order of Feature	2

$$y_t = f(y_{t-1}, y_{t-2}, y_{t-3}, \dots, y_{t-m}, x_t, x_{t-1}, x_{t-2}, x_{t-3}, \dots, x_{t-n})$$

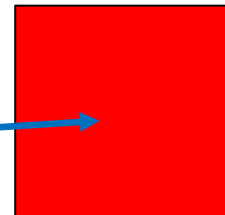
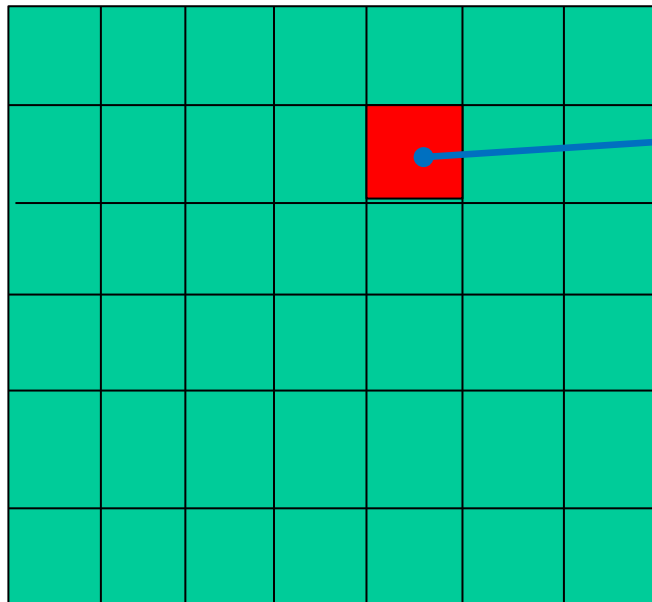
Hierarchical Matrix for Big Data

- Big matrix on CPU divided in small hierarchical matrices loadable on GPU with small memory
- Matrix computing on small GPU-memory possible
- Fast machine learning for big data

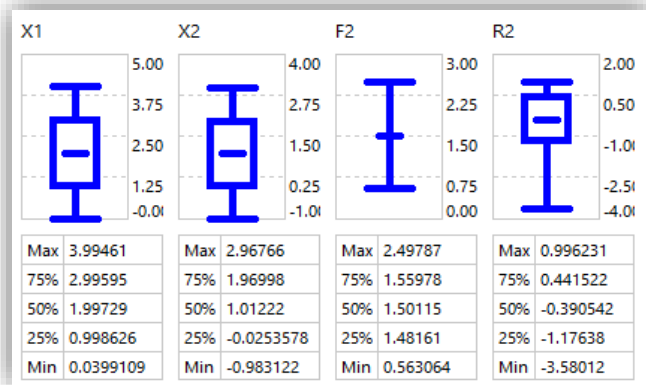
Hierarchical Matrix	
Big Data	Automatic
Max. Matrix Size	32

Big Matrix divided in Hierarchical Matrices on CPU

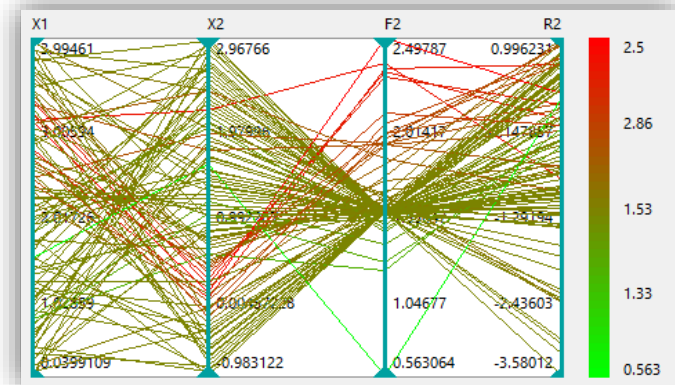
Small GPU Memory



New Graphical Presentations (DirectX 12)



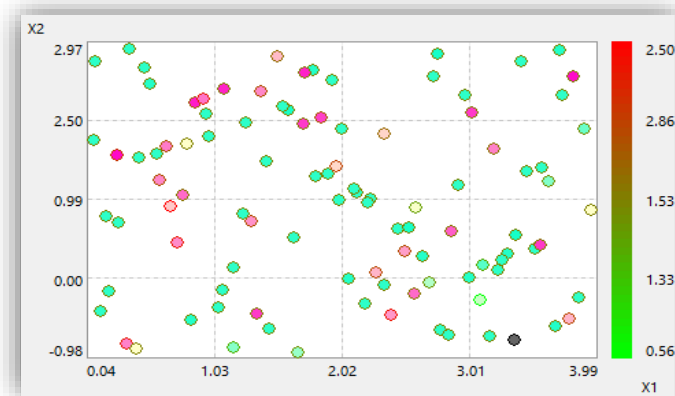
Box-Plot



Parallel Chart

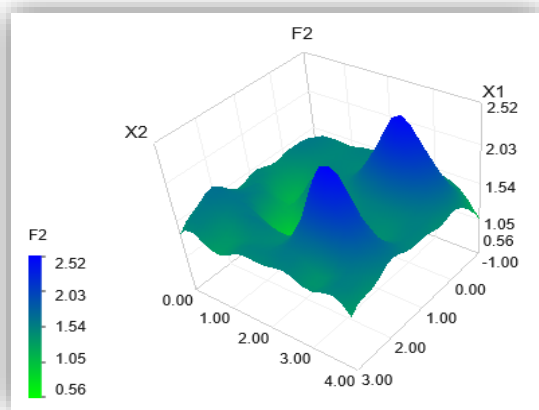
	X-Actuator-Position		Y-Actuator-Position		Max. Stress von Mises	
Plunger Length	3.88	3.88	10.20	10.20	16.27	16.29
Bracket High 1	0.00	0.00	0.07	0.07	0.31	0.32
Bracket High 2	6.36	6.36	13.75	13.75	1.73	1.74
Link 2 Length	24.46	24.46	48.05	48.05	47.85	47.92
Piston Length	0.00	0.00	0.05	0.05	0.41	0.41
Link 1 Length	0.00	0.00	0.07	0.07	0.34	0.34
Casing Length	56.17	56.17	0.00	0.00	0.20	0.20

Sensitivity Matrix

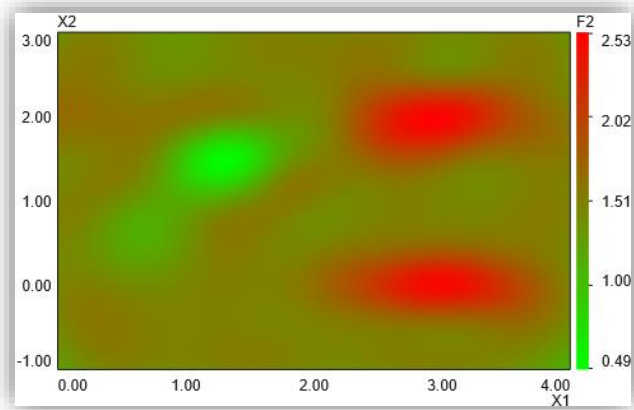


2D Scatter-Plot

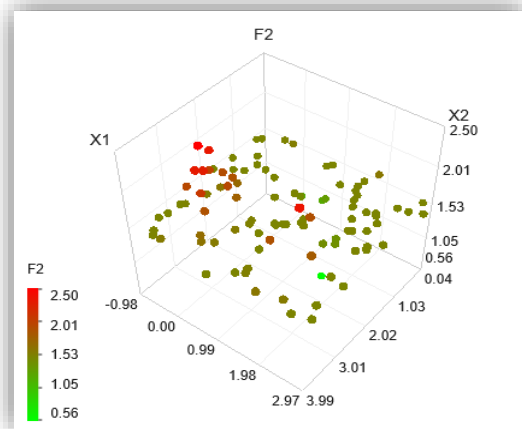
New Graphical Presentations (DirectX 12)



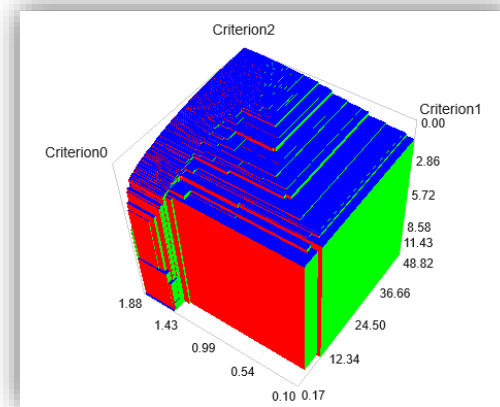
3D Surface



2D Surface

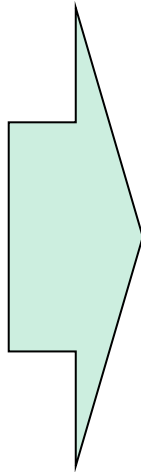
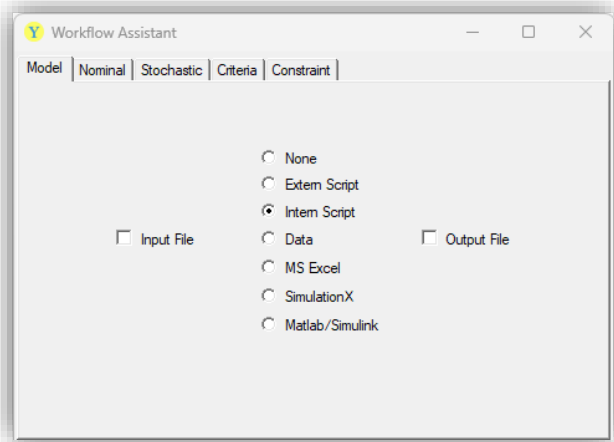


3D Scatter-Plot



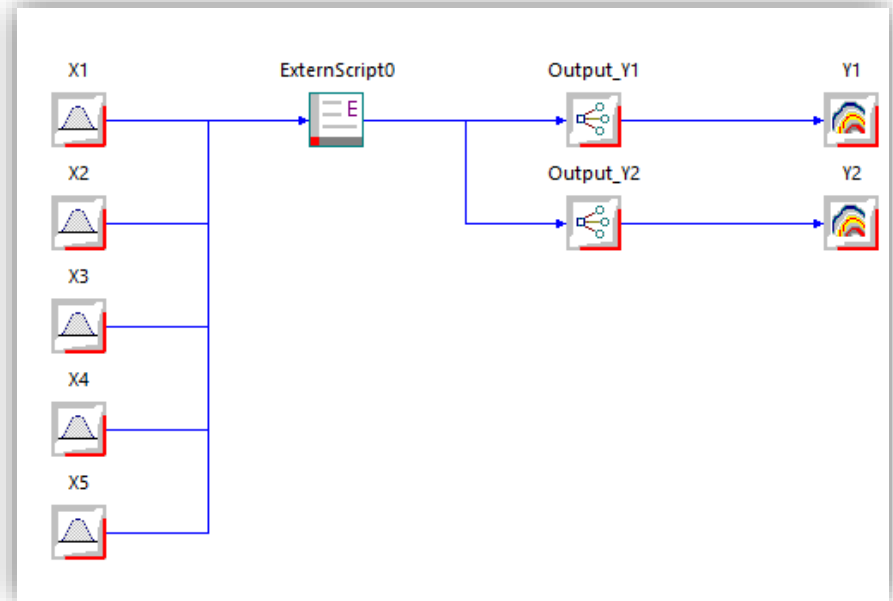
3D Hypervolume

Workflow Assistant



Name	Nominal	Tolerance
X1	2	2.2
X2	1	2.6
X3	3	2.5
X4	2	1.6
X5	4	0.2

Automatic Workflow Creation



Many Small Enhancements

- User-defined sampling on the meta-model and save in data-table
- Selection of input parameters for metamodel
- String as model parameter for “Input File”
- PowerShell is the new scripting for “Extern Script”
- Debug-mode for “Output File” with the option “Show Failure”
- Differential evolution method is implemented
- Improved Hooke-Jeeves method
- User-defined start values for evolution strategies and differential evolution
- New design of experiment method “ $2n+1$ ” is implemented
- Data import in “Nominal- and Stochastic-Editor” for parameter values
- Data export for correlation matrix
- Scatter-Plot can show data from different experiments as cluster